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Separating Milliken-Taylor Systems with Negative Entries¹

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Abstract. Given a finite sequence $\vec{a} = \langle a_i \rangle_{i=1}^n$ in N and a sequence $\langle x_t \rangle_{t=1}^\infty$ in N, the Milliken-Taylor system generated by \vec{a} and $\langle x_t \rangle_{t=1}^\infty$ is $MT(\vec{a}, \langle x_t \rangle_{t=1}^\infty) = \{\sum_{i=1}^n a_i \cdot \sum_{t \in F_i} x_t : F_1, F_2, \ldots, F_n \text{ are finite nonempty subsets of N with max } F_i < \min F_{i+1} \text{ for } i < n \}$. It is known that Milliken-Taylor systems are partition regular but not consistent. More precisely if \vec{a} and \vec{b} are finite sequences in N, then except in trivial cases, there is a partition of N into two cells, neither of which contains $MT(\vec{a}, \langle x_t \rangle_{t=1}^\infty) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^\infty)$ for any sequences $\langle x_t \rangle_{t=1}^\infty$ and $\langle y_t \rangle_{t=1}^\infty$. Our aim in this paper is to extend the above result to allow negative entries in

Our aim in this paper is to extend the above result to allow negative entries in \vec{a} and \vec{b} . We do so with a proof which is significantly shorter and simpler than the original proof which applied only to positive coefficients. We also derive some results concerning the existence of solutions of certain linear equations in $\beta \mathbb{Z}$. In particular we show that the ability to guarantee the existence of $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty})$ in one cell of a partition is equivalent to the ability to find idempotents p and q in $\beta \mathbb{N}$ such that $a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot q + b_2 \cdot q + \ldots + b_m \cdot q$, and thus determine exactly when the latter has a solution.

1. Introduction

There are striking differences between finite and infinite partition regular systems of linear expressions. To make this assertion precise, we remind the reader of the notion of an image partition regular matrix. (We are taking \mathbb{N} to be the set of positive integers.)

1.1 Definition. Let A be a (finite or infinite) matrix with entries from \mathbb{Z} and only finitely many nonzero entries on each row. Then A is *image partition regular* if and only if whenever \mathbb{Z} is partitioned into finitely many classes (or *finitely colored*) there exists a vector \vec{x} of the appropriate size with entries from \mathbb{N} such that all entries of $A\vec{x}$ are in the same class (or *monochrome*).

¹ Dedicated to the memory of Walter Deuber.

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Image partition regular matrices arise naturally in Ramsey Theory. For example, van der Waerden's Theorem and Schur's Theorem are naturally stated as the assertion that certain matrices are image partition regular. See [5], [6], or [8, Chapter 15] for more extensive discussions of image partition regular matrices. (One of the major differences between finite and infinite image partition regular matrices is that the former have been completely characterized [5], while the characterization of infinite image partition regular matrices is a vexing open problem. It is not this difference with which we are concerned in this paper, however.)

It is a consequence of a result of Deuber [2] and some results from [5] that whenever A and B are finite image partition regular matrices, then so is the matrix $\begin{pmatrix} A & \mathbf{O} \\ \mathbf{O} & B \end{pmatrix}$. That is, whenever \mathbb{Z} is finitely colored, there must exist vectors \vec{x} and \vec{y} of the appropriate size with entries from \mathbb{N} such that all entries of $A\vec{x}$ and $B\vec{y}$ have the same color. This is far from the case with infinite image partition regular matrices. To further this discussion, we introduce the notion of Milliken-Taylor systems. Given a set A, we denote the set of finite nonempty subsets of A by $\mathcal{P}_f(A)$.

1.2 Definition. Let $\vec{a} = \langle a_i \rangle_{i=1}^n$ be a finite sequence in $\mathbb{Z} \setminus \{0\}$ and let $\langle x_t \rangle_{t=1}^\infty$ be a sequence in \mathbb{N} . The *Milliken-Taylor system* $MT(\vec{a}, \langle x_t \rangle_{t=1}^\infty)$ generated by \vec{a} and $\langle x_t \rangle_{t=1}^\infty$ is $\{\sum_{i=1}^n a_i \cdot \sum_{t \in F_i} x_t : F_1, F_2, \ldots, F_n \in \mathcal{P}_f(\mathbb{N}) \text{ and } \max F_i < \min F_{i+1} \text{ for } i < n\}$.

Milliken-Taylor systems are so named because their partition regularity follows immediately from the Milliken-Taylor Theorem ([10, Theorem 2.2], [11, Lemma 2.2]).

1.3 Definition. Let $\langle y_n \rangle_{n=1}^{\infty}$ and $\langle x_n \rangle_{n=1}^{\infty}$ be sequences in \mathbb{N} . The sequence $\langle x_n \rangle_{n=1}^{\infty}$ is a sum subsystem of $\langle y_n \rangle_{n=1}^{\infty}$ if and only if there is a sequence $\langle H_n \rangle_{n=1}^{\infty}$ in $\mathcal{P}_f(\mathbb{N})$ with $\max H_n < \min H_{n+1}$ for each $n \in \mathbb{N}$ and $x_n = \sum_{\ell \in H_n} y_\ell$ for each $n \in \mathbb{N}$.

Notice that if $\langle x_n \rangle_{n=1}^{\infty}$ is a sum subsystem of $\langle y_n \rangle_{n=1}^{\infty}$, then $FS(\langle x_n \rangle_{n=1}^{\infty}) \subseteq FS(\langle y_n \rangle_{n=1}^{\infty})$, where $FS(\langle x_n \rangle_{n=1}^{\infty}) = \{\sum_{n \in F} x_n : F \in \mathcal{P}_f(\mathbb{N})\} = MT(\langle 1 \rangle, \langle x_n \rangle_{n=1}^{\infty}).$

Not only are Milliken-Taylor systems partition regular, but in fact the following stronger result is true.

1.4 Theorem. Let \vec{a} be a finite sequence in \mathbb{N} and let $\langle y_n \rangle_{n=1}^{\infty}$ be a sequence in \mathbb{N} . Let $r \in \mathbb{N}$ and let $\mathbb{N} = \bigcup_{i=1}^r B_i$. Then there exist $i \in \{1, 2, \ldots, r\}$ and a sum subsystem $\langle x_n \rangle_{n=1}^{\infty}$ of $\langle y_n \rangle_{n=1}^{\infty}$ with $MT(\vec{a}, \langle x_n \rangle_{n=1}^{\infty}) \subseteq B_i$.

Proof. [3, Theorem 2.5].

We can now describe the striking difference between finite and infinite image partition regular matrices with which we are concerned. Consider for example the matrix A

whose rows consist of all rows with entries from $\{0, 1, 2\}$ with only finitely many nonzero entries, at least one 1, at least one 2, and all occurrences of 1 before any ocurrences of 2. Consider also the matrix *B* whose rows consist of all rows with entries from $\{0, 1, 2\}$ with only finitely many nonzero entries, at least one 1, at least one 2, and all occurrences of 2 before any ocurrences of 1. Then given a sequence $\vec{x} = \langle x_n \rangle_{n=1}^{\infty}$, the set of entries of $A\vec{x}$ is $MT(\langle 1, 2 \rangle, \langle x_n \rangle_{n=1}^{\infty})$ and the set of entries of $B\vec{x}$ is $MT(\langle 2, 1 \rangle, \langle x_n \rangle_{n=1}^{\infty})$. Thus, by Theorem 1.3, the matrices *A* and *B* are image partition regular. On the other hand, it was shown in [3, Theorem 3.3] that $\begin{pmatrix} A & \mathbf{O} \\ \mathbf{O} & B \end{pmatrix}$ is not image partition regular. And we can say more. We know exactly when such matrices can be combined to yield an image partition regular matrix.

1.5 Definition. Let $\vec{a} = \langle a_i \rangle_{i=1}^n$ be a finite sequence. Then \vec{a} is a *compressed* sequence if and only if \vec{a} has no adjacent repeated terms.

We note that, as far as partition regularity is concerned, we lose no generality by restricting our attention to compressed sequences \vec{a} . In the following lemma, if we had $\vec{a} = \langle 2, -3, -3, 1, 1, 1, 1, 2 \rangle$, then we would have $\vec{c} = \langle 2, -3, 1, 2 \rangle$.

1.6 Lemma. Let \vec{a} be a finite sequence in $\mathbb{Z}\setminus\{0\}$ and let \vec{c} be the compressed sequence obtained by deleting adjacent repetitions of terms. Let $\langle y_n \rangle_{n=1}^{\infty}$ be a sequence in \mathbb{N} . Then there is a sum subsystem $\langle x_n \rangle_{n=1}^{\infty}$ of $\langle y_n \rangle_{n=1}^{\infty}$ such that $MT(\vec{c}, \langle x_n \rangle_{n=1}^{\infty}) \subseteq MT(\vec{a}, \langle y_n \rangle_{n=1}^{\infty})$.

Proof. Let *m* be the length of \vec{a} and for $k \in \mathbb{N}$, let $H_k = \{(k-1)m + 1, (k-1)m + 2, \ldots, km\}$ and let $x_k = \sum_{t \in H_k} y_t$.

The main result of [3] determined precisely when one could guarantee Milliken-Taylor systems for \vec{a} and \vec{b} in the same cell of an arbitrary partition of \mathbb{N} , provided that the entries of \vec{a} and \vec{b} are positive.

1.7 Theorem. Let \vec{a} and \vec{b} be finite compressed sequences with entries from \mathbb{N} . The following statements are equivalent.

- (a) Whenever $r \in \mathbb{N}$ and $\mathbb{N} = \bigcup_{i=1}^{r} B_i$, there exist $i \in \{1, 2, \dots, r\}$ and sequences $\langle x_n \rangle_{n=1}^{\infty}$ and $\langle y_n \rangle_{n=1}^{\infty}$ with $MT(\vec{a}, \langle x_n \rangle_{n=1}^{\infty}) \cup MT(\vec{b}, \langle y_n \rangle_{n=1}^{\infty}) \subseteq B_i$.
- (b) There is a positive rational number α such that $\vec{b} = \alpha \cdot \vec{a}$.

Proof. [3, Theorems 3.2 and 3.3].

In the definition of partition regularity of matrices, the requirement that the entries of $\langle x_n \rangle_{n=1}^{\infty}$ be positive is there because that is desired in the typical classical Ramsey

Theoretic applications. At the time that [3] was written, it did not occur to the authors to ask what happens when the entries of \vec{a} are allowed to be negative. Had it ocurred to them, they could have presented the following result, which was first stated in [6, Corollary 3.6].

1.8 Theorem. Let \vec{a} be a finite sequence in $\mathbb{Z}\setminus\{0\}$ and let $\langle y_n \rangle_{n=1}^{\infty}$ be a sequence in \mathbb{N} . Let $r \in \mathbb{N}$ and let $\mathbb{Z} = \bigcup_{i=1}^{r} B_i$. Then there exist $i \in \{1, 2, \ldots, r\}$ and a sum subsystem $\langle x_n \rangle_{n=1}^{\infty}$ of $\langle y_n \rangle_{n=1}^{\infty}$ with $MT(\vec{a}, \langle x_n \rangle_{n=1}^{\infty}) \subseteq B_i$.

Proof. The proof of [3, Theorem 2.5] may be copied verbatim.

Further, if in Theorem 1.7 the entries of \vec{a} and \vec{b} are allowed to be negative, then one may take the proof that (b) implies (a) directly from the proof of [3, Theorem 3.2].

The matter of the proof that (a) implies (b) in the revised Theorem 1.7 is considerably more complicated. In the first place, the proof of [3, Theorem 3.3] is lengthy and at least moderately intricate. In the second place, that proof does not easily accomodate the inclusion of negative numbers. The reason has to do with the difference between the addition and subtraction algorithms in our ordinary arithmetic (to a specified positive base).

It is easy to see that, given $p \in \mathbb{N}$ and a sequence $\langle y_n \rangle_{n=1}^{\infty}$ in \mathbb{N} , there is a sum subsystem $\langle x_n \rangle_{n=1}^{\infty}$ of $\langle y_n \rangle_{n=1}^{\infty}$ with the property that for any $t, n \in \mathbb{N}$, if $x_n \leq p^t$, then p^{t+1} divides x_{n+1} , and consequently there is no carrying when x_n and x_{n+1} are added in base p arithmetic. This fact allowed a coloring of \mathbb{N} based on patterns which occurred in the base p expansion of members of \mathbb{N} which could separate $MT(\vec{a}, \langle x_n \rangle_{n=1}^{\infty})$ from $MT(\vec{b}, \langle y_n \rangle_{n=1}^{\infty})$ for any sequences $\langle x_n \rangle_{n=1}^{\infty}$ and $\langle y_n \rangle_{n=1}^{\infty}$, as long as one did not have $\vec{b} = \alpha \cdot \vec{a}$ for any positive rational α .

However, even under these conditions, there is borrowing when x_n is subtracted from x_{n+1} . The fact that the string of zeroes between the least significant digit of x_{n+1} and the most significant digit of x_n is replaced by a string of (p-1)'s is not a serious problem, but the change in the least significant digit of x_{n+1} caused by the borrowing seriously disrupts the patterns of digits. This fact caused us significant problems. Then we recalled a lecture that two of us heard at the University of Sheffield in 1996 at which Behzad Bordbar discussed some joint research with John Pym [1] which utilized the fact that any integer (positive, zero, or negative) has a unique expansion to the base -2(using only the digits 0 and 1). A moment's reflection will convince the reader that the same statement is true with regard to base -p, using the digits $\{0, 1, \ldots, p-1\}$. There are two important properties of this expansion. The first is that a number is divisible by p^t if and only if the rightmost t digits are 0. The second is that, when $t \in \mathbb{N}$, $x, y \in \mathbb{Z}$, $|x| \leq p^t$, and p^{t+1} divides y, then there is no carrying and no borrowing when x and y are added in base -p. This fact allows us to modify the construction of [3] and establish the analogue of Theorem 1.7 which allows entries of \vec{a} and \vec{b} to be negative.

In Section 2 of this paper we present some relevant facts about negative base arithmetic and some special functions that we will use. In Section 3 we complete the proof of the analogue of Theorem 1.7. In Section 4 we present additional equivalent conditions dealing with the solution of certain linear equations in the Stone-Čech compactification of \mathbb{Z} .

2. Arithmetic in base -p

We begin with the description of the base -p expansion and some routine facts about that expansion, whose proofs we omit. (We take $\omega = \mathbb{N} \cup \{0\}$.)

2.1 Lemma. Let $p \in \mathbb{N}$ with $p \geq 2$. For every $x \in \mathbb{Z}$, there exists a unique function $\gamma_{p,x} : \omega \to \{0, 1, \dots, p-1\}$ (with $\{t \in \omega : \gamma_{p,x}(t) \neq 0\}$ finite) such that

$$x = \sum_{t=0}^{\infty} \gamma_{p,x}(t) \cdot (-p)^t$$

If x > 0, then $\max\{t \in \omega : \gamma_{p,x}(t) \neq 0\}$ is even and if x < 0, then $\max\{t \in \omega : \gamma_{p,x}(t) \neq 0\}$ is odd. For any $x \in \mathbb{Z} \setminus \{0\}$ and any $n \in \mathbb{N}$, p^n divides x if and only if $\min\{t \in \omega : \gamma_{p,x}(t) \neq 0\} \ge n$.

Given $x \in \mathbb{Z} \setminus \{0\}$ and $p \in \mathbb{N} \setminus \{1\}$ if $\alpha = \max\{t \in \omega : \gamma_{p,x}(t) \neq 0\}$, we refer to $\gamma_{p,x}(\alpha)$ as the most significant digit of x in the base -p expansion and we refer to α as the location of the most significant digit. Similarly, if $\delta = \min\{t \in \omega : \gamma_{p,x}(t) \neq 0\}$, then $\gamma_{p,x}(\delta)$ is the least significant digit and δ is its location.

2.2 Lemma. Let $p \in \mathbb{N} \setminus \{1\}$, let $t \in \mathbb{N}$, and let $x \in \mathbb{Z} \setminus \{0\}$. If x is expressible in base -p with most significant digit in location t, then

$$\frac{p^t}{p+1} < |x| < \frac{p^{t+2}}{p+1}$$

Proof. If t is even, this follows easily from the inequalities:

$$p^{t} - (p-1)(p^{t-1} + p^{t-3} + \dots + p) \le x \le (p-1)(p^{t} + p^{t-2} + \dots + p^{2} + 1).$$

If t is odd, our claim then follows from the inequalities:

$$\frac{p^{t+1}}{p+1} < -px = p|x| < \frac{p^{t+3}}{p+1}.$$

2.3 Corollary. Let $a, x \in \mathbb{Z} \setminus \{0\}$, with |a| < p. If the most significant digits of x and ax in their base -p expansions occur in positions t and u respectively, then $t-1 \le u \le t+2$.

Proof. This is immediate from the inequalities:

$$\frac{p^t}{p+1} < |x| \le |ax| < \frac{p^{t+3}}{p+1} \text{ and}$$
$$\frac{p^u}{p+1} < |ax| < \frac{p^{u+2}}{p+1}.$$

We now introduce some special functions which we will use to define colorings of \mathbb{Z} .

2.4 Definition. Let $p \in \mathbb{N} \setminus \{1\}$.

- (a) For each $x \in \mathbb{Z} \setminus \{0\}$, we define $\rho_p(x) \in \{1, 2, \dots, p-1\}$ to be the least significant digit in the base -p expansion of x.
- (b) If $x \in \mathbb{Z}$ with $|x| > p^{11}$, we define $\lambda_p(x) \in \{0, 1, 2, \dots, p-1\}^{11}$ by $\lambda_p(x) = (v_1, v_2, \dots, v_{11})$, where $v_1 v_2 \cdots v_{11}$ occurs in the base -p expansion of x with v_1 at a location t which is a multiple of 6, and the most significant digit of the expansion occurs at location s with $t-5 \leq s \leq t$.

Notice that if $\lambda_p(x) = \lambda_p(y)$, then the most significant digits of x and y occur in positions that are congruent mod 6 (hence mod 2) and thus x and y have the same sign.

2.5 Lemma. Let $p \ge 3$ be a prime. Let $x, y \in \mathbb{Z} \setminus \{0\}$ and let $a, b, c \in \mathbb{Z} \setminus \{0\}$ satisfy |a|, |b|, |c|, |a - b| < p.

(i) If
$$\rho_p(ax) = \rho_p(bx)$$
, then $a = b$.

(ii) If $|x|, |y| > p^{11}$ and if $\lambda_p(cx) = \lambda_p(cy)$ and $\lambda_p(ax) = \lambda_p(by)$, then a = b.

Proof. (i). If $\rho_p(x) = \rho_p(y) = u$, then $au \equiv bu \pmod{p}$ and so a = b.

(ii). Let t, t', u, u', v, v' denote the locations of the most significant digits of x, y, ax, by, cx, cy respectively in their base -p expansions.

We may suppose that u = u'. If u' > u, we can replace x by $(-p)^{u'-u}x$. Since $u \equiv u' \pmod{6}$, this does not alter $\lambda_p(ax)$ or $\lambda_p(cx)$. If u' < u, we can replace y by $(-p)^{u-u'}y$.

We claim that v = v'. We suppose that $t' \ge t$, the other case being similar. By Corollary 2.3, $t' - 1 \le u' = u \le t + 2$. So $t' \le t + 3$. However, x and y have the same sign, because cx and cy have the same sign, and therefore t and t' have the same parity. Thus $t' \le t + 2$. Now $t - 1 \le v \le t + 2$ and $t - 1 \le t' - 1 \le v' \le t' + 2 \le t + 4$. Since $v \equiv v' \pmod{6}, v = v'$.

We have

$$ax = w_1(-p)^u + w_2(-p)^{u-1} + \dots + w_6(-p)^{u-5} + z \text{ and}$$

$$by = w_1(-p)^u + w_2(-p)^{u-1} + \dots + w_6(-p)^{u-5} + z',$$

where $w_1, w_2, w_3, w_4, w_5, w_6 \in \{0, 1, 2, \dots, p-1\}$ and $|z|, |z'| < \frac{p^{u-4}}{p+1} \le \frac{p^{t-2}}{p+1}$. So $|ax - by| < 2\frac{p^{t-2}}{p+1}$. Similarly, $|x - y| \le |c(x - y)| < 2\frac{p^{t-2}}{p+1}$ and so $|bx - by| < 2\frac{p^{t-1}}{p+1}$. Thus $|(b - a)x| \le 2\frac{p^{t-1}}{p+1} + 2\frac{p^{t-2}}{p+1} < \frac{p^t}{p+1} < |x|$ so b = a.

We remark that it is the above proof which forces us to require 11 digits in $\lambda_p(x)$. If $\lambda_p(ax) = \lambda_p(bx) = (v_1, v_2, \dots, v_{11})$, then one could have $u = v_6$, in which case $(w_1, w_2, \dots, w_6) = (v_6, v_7, \dots, v_{11})$.

3. Separating
$$MT(\overrightarrow{a}, \langle x_n \rangle_{n=1}^{\infty})$$
 from $MT(\overrightarrow{b}, \langle y_n \rangle_{n=1}^{\infty})$

We shall be concerned in this section with establishing the generalization of Theorem 1.7 which allows entries of \vec{a} and \vec{b} to be negative. The proof that we present of the generalization turns out to be significantly simpler and shorter than the original proof.

3.1 Theorem. Let \vec{a} and \vec{b} be finite compressed sequences with entries from $\mathbb{Z} \setminus \{0\}$. The following statements are equivalent.

- (a) Whenever $r \in \mathbb{N}$ and $\mathbb{Z} = \bigcup_{i=1}^{r} B_i$, there exist $i \in \{1, 2, \dots, r\}$ and sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} with $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty}) \subseteq B_i$.
- (b) There is a positive rational number α such that $\vec{b} = \alpha \cdot \vec{a}$.

Proof. (b) implies (a). Pick positive integers m and n such that $\alpha = \frac{m}{n}$ and let $\vec{d} = m\vec{a}$. Assume that $r \in \mathbb{N}$ and $\mathbb{Z} = \bigcup_{i=1}^{r} B_i$. Pick by Theorem 1.8 $i \in \{1, 2, \ldots, r\}$ and a sequence $\langle z_t \rangle_{t=1}^{\infty}$ in \mathbb{N} such that $MT(\vec{d}, \langle z_t \rangle_{t=1}^{\infty}) \subseteq B_i$. For each $t \in \mathbb{N}$, let $x_t = mz_t$ and let $y_t = nz_t$. Then $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) = MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty}) = MT(\vec{d}, \langle z_t \rangle_{t=1}^{\infty})$.

The proof that (a) implies (b) will include several definitions and lemmas. We assume that we have compressed sequences $\vec{a} = \langle a_1, a_2, \ldots, a_n \rangle$ and $\vec{b} = \langle b_1, b_2, \ldots, b_m \rangle$ with entries from $\mathbb{Z} \setminus \{0\}$ such that whenever \mathbb{Z} is finitely colored there exist sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} with $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty})$ monochrome.

We choose a prime number p such that $p > 2|a_i| + 2|b_j|$ for every $i \in \{1, 2, ..., n\}$ and every $j \in \{1, 2, ..., m\}$. We also choose an even positive integer k such that k > 2m + 2n. We use $\pi : \mathbb{Z} \to \mathbb{Z}_k$ for the canonical homomorphism, and we represent \mathbb{Z}_k as $\{0, 1, \ldots, k-1\}$.

3.2 Definition. Let $x \in \mathbb{N}$. Then $\operatorname{supp}(x) = \{t \in \omega : \gamma_{p,x}(t) \neq 0\}$.

In the above definition we suppress the dependence of $\operatorname{supp}(x)$ on p, because p will remain fixed throughout the remainder of this section. Similarly, we shall write $\rho(x)$ and $\lambda(x)$ instead of $\rho_p(x)$ and $\lambda_p(x)$

3.3 Lemma. Let $\langle x_t \rangle_{t=1}^{\infty}$ be an arbitrary sequence in \mathbb{N} .

- (a) Given any $b \in \mathbb{N}$, there is a sum subsytem $\langle u_t \rangle_{t=1}^{\infty}$ of $\langle x_t \rangle_{t=1}^{\infty}$ such that $FS(\langle u_t \rangle_{t=1}^{\infty}) \subseteq b\mathbb{N}$.
- (b) There is a sum subsystem $\langle y_t \rangle_{t=1}^{\infty}$ of $\langle x_t \rangle_{t=1}^{\infty}$ such that for each $t \in \mathbb{N}$, min $(\operatorname{supp}(y_{t+1})) \ge 13 + \max(\operatorname{supp}(y_t)).$
- (c) Given any finite coloring of \mathbb{N} and any $b \in \mathbb{N}$, there is a sum subsystem $\langle z_t \rangle_{t=1}^{\infty}$ of $\langle x_t \rangle_{t=1}^{\infty}$ such that $FS(\langle z_t \rangle_{t=1}^{\infty}) \subseteq b\mathbb{N}$, $FS(\langle z_t \rangle_{t=1}^{\infty})$ is monchrome, and for each $t \in \mathbb{N}$, min $(\operatorname{supp}(z_{t+1})) \geq 13 + \max(\operatorname{supp}(y_t))$.

Proof. (a). By thinning, we may presume that $x_t \equiv x_s \pmod{b}$ for all $t, s \in \mathbb{N}$. For each $s \in \mathbb{N}$, let $H_s = \{sb, sb+1, sb+2, \dots, (s+1)b-1\}$ and let $u_s = \sum_{t \in H_s} x_t$.

(b). Let $H_1 = \{1\}$ and let $y_1 = x_1$. Inductively, given $s \in \mathbb{N}$, assume that we have chosen H_s and $y_s = \sum_{t \in H_s} x_t$. Let $r = 13 + \max(\operatorname{supp}(y_s))$. Choose $H_{s+1} \subseteq \{i \in \mathbb{N} : i > \max(H_s)\}$ such that $|H_{s+1}| = p^r$ and $x_i \equiv x_j \pmod{p^r}$ for all $i, j \in H_{s+1}$. Let $y_{s+1} = \sum_{t \in H_{s+1}} x_t$. Then p^r divides y_{s+1} , so $\min(\operatorname{supp}(y_{s+1})) \ge r$.

(c). Using (a), choose a sum subsytem $\langle u_t \rangle_{t=1}^{\infty}$ of $\langle x_t \rangle_{t=1}^{\infty}$ such that $FS(\langle u_t \rangle_{t=1}^{\infty}) \subseteq b\mathbb{N}$. Using (b), choose a sum subsystem $\langle y_t \rangle_{t=1}^{\infty}$ of $\langle u_t \rangle_{t=1}^{\infty}$ such that for each $t \in \mathbb{N}$, min $(\operatorname{supp}(y_{t+1})) \geq 13 + \max(\operatorname{supp}(y_t))$. Using [8, Corollary 5.15], choose a sum subsystem $\langle z_t \rangle_{t=1}^{\infty}$ of $\langle y_t \rangle_{t=1}^{\infty}$ such that $FS(\langle z_t \rangle_{t=1}^{\infty})$ is monchrome.

3.4 Definition.

- (a) $V = \{ \vec{v} \in \{0, 1, 2, \dots, p-1\}^{11} : (v_1, v_2, \dots, v_6) \neq \vec{0} \}.$
- (b) If $x \in \mathbb{Z} \setminus \{0\}$, then $G(x) = \{(t, u, \vec{v}) \in \mathbb{N} \times \{1, 2, \dots, p-1\} \times V : u00 \cdots 0v_1v_2v_3 \cdots v_{11}$ occurs in the base -p expansion of x, with u in location t, v_1 in a location which is a multiple of 6 and at least one zero occurring between u and $v_1\}$.

A gap of x is any member of G(x). We shall refer to $(t, u, \vec{v}) \in G(x)$ as a (u, \vec{v}) -gap of x. The following simple lemma is the key to our counting of gaps.

3.5 Lemma. Let $|x_1| > p^{11}$ and assume that $\max(\operatorname{supp}(x_1)) + 11 \le s = \min(\operatorname{supp}(x_2))$, then $G(x_1 + x_2) = G(x_1) \cup G(x_2) \cup \{(s, \rho(x_2), \lambda(x_1))\}.$

Proof. We leave most of the details to the reader, only pointing out the two places where we use the assumption that $\max(\operatorname{supp}(x_1)) + 11 \leq \min(\operatorname{supp}(x_2))$. Let $r = \max(\operatorname{supp}(x_1))$. If (t, u, \vec{v}) is a gap of x_2 so that $u00\cdots 0v_1v_2v_3\cdots v_{11}$ occurs in the base -p expansion of x_2 , with u in location t and v_1 in location j, then $j \geq s \geq r + 11$ so $u00\cdots 0v_1v_2v_3\cdots v_{11}$ occurs in the expansion of $x_1 + x_2$, with u in location t.

Similarly, if (t, u, \vec{v}) is a gap of $x_1 + x_2$ with t > s, so that $u00 \cdots 0v_1v_2v_3 \cdots v_{11}$ occurs in the expansion of $x_1 + x_2$, with u in location t, and v_1 occurs in location j, then $j \ge s \ge r + 11$ so none of the digits of \vec{v} come from x_1 and thus (t, u, \vec{v}) is a gap of x_2 .

3.6 Definition. Let $x \in \mathbb{Z} \setminus \{0\}$.

- (a) For $(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V$, $G_{(u, \vec{v})}(x) = \{t \in \mathbb{N} : (t, u, \vec{v}) \in G(x)\}.$
- (b) For $(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V$, $g_{(u,\vec{v})}(x) = |G_{(u,\vec{v})}(x)|$.
- (c) $P(x) = \{(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V : \pi(g_{(u, \vec{v})}(x)) \in \{1, 2, \dots, \frac{k}{2}\}\}.$

Thus $G_{(u,\vec{v})}(x)$ is the set of locations of (u, \vec{v}) -gaps of x and $g_{(u,\vec{v})}(x)$ is the number of (u, \vec{v}) -gaps of x. We shall only be concerned with (u, \vec{v}) -gaps of x for $(u, \vec{v}) \in P(x)$. We pause to give an informal description of the procedure we shall follow to prove that (a) implies (b) in Theorem 3.1.

Let $x = a_n w_n + \ldots + a_2 w_2 + a_1 w_1$, where $\langle w_t \rangle_{t=1}^{\infty}$ is a suitable sum subsystem of $\langle x_t \rangle_{t=1}^{\infty}$. One counts gaps in the expansion of x. What is a bit confusing is that one has to do this more than once.

- (1) Firstly, for a given (u, \vec{v}) , one counts the number of corresponding gaps in order to decide whether (u, \vec{v}) is in P(x) (i.e. whether the number of (u, \vec{v}) -gaps is less than or equal to $\frac{k}{2} \pmod{k}$).
- (2) Then, for each gap $(t, u, \vec{v}) \in G(x)$, with (u, \vec{v}) in P(x), one counts the number of gaps in P(x) which occur to the right of the given one.
- (3) Then, keeping (u, \vec{v}) fixed, for each $i \in \{0, 1, ..., n-2\}$, one counts the number of values of t for which the number obtained in (2) is equal to $i \pmod{k}$.
- (4) Finally, one asks whether the number obtained in (3) is equal to 1 (mod k). If it is, the gap which occurs between $a_{i+2}w_{i+2}$ and $a_{i+1}w_{i+1}$ is a (u, \vec{v}) -gap.

To indicate why this works:

Firstly, (u, \vec{v}) is in P(x) if and only if it occurs between $a_{i+1}w_{i+1}$ and a_iw_i for some i. If one looks at the expansion of x and makes the simple minded assumption that the gaps in P(x) occur only in this way, and never occur internally inside the expansion of some a_iw_i , then the gap between $a_{i+2}w_{i+2}$ and $a_{i+1}w_{i+1}$ is distinguished from the others because it is the only one in P(x) with i gaps of P(x) to its right. Of course,

this assumption is likely to be false. However, one gets the same answer in (4) as one would if it were true. The reason is that, for the gap between $a_{i+1}w_{i+1}$ and a_iw_i , the number of internal gaps in P(x) to its right is congruent to 0 (mod k). So whether this gap is counted in (3) or not is unaffected by the internal gaps. Furthermore, the number of internal gaps counted in (3) is congruent to 0 (mod k). So the answer in (4) is unaffected by the internal gaps.

3.7 Lemma. Let $\langle x_t \rangle_{t=1}^{\infty}$ be a sequence in $\mathbb{Z} \setminus \{0\}$ such that $|x_1| > p^{11}$ and $\max(\operatorname{supp}(x_t)) + 11 \leq \min(\operatorname{supp}(x_{t+1}))$ for every $t \in \mathbb{N}$. Suppose that there exist $u \in \{1, 2, \ldots, p-1\}$ and $\vec{v} \in V$ such that $\rho(x) = u$ and $\lambda(x) = \vec{v}$ for every $x \in FS(\langle x_t \rangle_{t=1}^{\infty})$. Let $w \in \{1, 2, \ldots, p-1\}$, let $\vec{z} \in V$, let $r \in \{0, 1, \ldots, k-1\}$, and assume that $g_{(w,\vec{z})}(x) \equiv r \pmod{k}$ for each $x \in FS(\langle x_t \rangle_{t=1}^{\infty})$.

(b) If $(w, \vec{z}) = (u, \vec{v})$, then r = k - 1.

Proof. If $(w, \vec{z}) \neq (u, \vec{v})$, then $G_{(w,\vec{z})}(x_1 + x_2) = G_{(w,\vec{z})}(x_1) \cup G_{(w,\vec{z})}(x_2)$ and so $g_{(w,\vec{z})}(x_1 + x_2) = g_{(w,\vec{z})}(x_1) + g_{(w,\vec{z})}(x_2)$. If $(w, \vec{z}) = (u, \vec{v})$ and min $(\operatorname{supp}(x_2)) = s$, then $G_{(w,\vec{z})}(x_1 + x_2) = G_{(w,\vec{z})}(x_1) \cup G_{(w,\vec{z})}(x_2) \cup \{s\}$ and so $g_{(w,\vec{z})}(x_1 + x_2) = g_{(w,\vec{z})}(x_1) + g_{(w,\vec{z})}(x_2) + 1$.

3.8 Lemma. Let $\langle x_t \rangle_{t=1}^{\infty}$ be a sequence in \mathbb{N} such that $x_1 > p^{11}$ and $\max(\operatorname{supp}(x_t)) + 13 \leq \min(\operatorname{supp}(x_{t+1}))$ for each $t \in \mathbb{N}$. Suppose that $\rho(a_i x) = \rho(a_i x')$ and $\lambda(a_i x) = \lambda(a_i x')$ for all $x, x' \in FS(\langle x_t \rangle_{t=1}^{\infty})$ and all $i \in \{1, 2, \ldots, n\}$. Suppose also that $g_{(w, \vec{z})}(a_i x) \equiv g_{(w, \vec{z})}(a_i x') \pmod{k}$ for all $x, x' \in FS(\langle x_t \rangle_{t=1}^{\infty})$, all $i \in \{1, 2, \ldots, n\}$, and all $(w, \vec{z}) \in \{1, 2, \ldots, p-1\} \times V$. If $x \in FS(\langle x_t \rangle_{t=1}^{\infty})$, $j \in \{1, 2, \ldots, n-1\}$, $w = \rho(a_{j+1}x)$, and $\vec{z} = \lambda(a_j x)$, then $g_{(w, \vec{z})}(a_i x) \equiv 0 \pmod{k}$ for all $i \in \{1, 2, \ldots, n\}$.

Proof. Let $i \in \{1, 2, ..., n\}$ and notice that the sequence $\langle a_i x_t \rangle_{t=1}^{\infty}$ satisfies the hypotheses of Lemma 3.7. (Given $t \in \mathbb{N}$, by Corollary 2.3 we have that $\max(\operatorname{supp}(a_i x_t)) + 11 \leq \max(\operatorname{supp}(x_t)) + 13 \leq \min(\operatorname{supp}(x_{t+1})) = \min(\operatorname{supp}(a_i x_{t+1})).$)

Let $j \in \{1, 2, ..., n-1\}$, let $w = \rho(a_{j+1}x_1)$, and let $\vec{z} = \lambda(a_jx_1)$. By Lemma 3.7 it suffices to show that $(w, \vec{z}) \neq (\rho(a_ix_1), \lambda(a_ix_1))$. Suppose instead that $\rho(a_{j+1}x_1) = \rho(a_ix_1)$ and $\lambda(a_jx_1) = \lambda(a_ix_1)$. Then by Lemma 2.5(i) we have immediately that $a_{j+1} = a_i$. By Lemma 2.5(ii), with $x = y = x_1$ and c = 1, we have that $a_j = a_i$. This contradicts the fact that \vec{a} is a compressed sequence.

We are now in a position to complete the proof of Theorem 3.1 by showing that (a) implies (b).

Proof that (a) implies (b).

Recall that we have been assuming that we have compressed sequences $\vec{a} = \langle a_1, a_2, \ldots, a_n \rangle$ and $\vec{b} = \langle b_1, b_2, \ldots, b_m \rangle$ with entries from $\mathbb{Z} \setminus \{0\}$ such that whenever \mathbb{Z} is finitely colored there exist sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} with $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty})$ monochrome. We show first that we may assume that $a_n = b_m \in \mathbb{N}$ (and then show that $\vec{a} = \vec{b}$). To see this note that a_n and b_m have the same sign. (If $\langle x_t \rangle_{t=1}^{\infty}$ is a sequence in \mathbb{N} and $F \in \mathcal{P}_f(\mathbb{N})$ such that $\min F \geq n$ and $\sum_{t \in F} x_t > |\sum_{i=1}^{n-1} a_i x_i|$, then $a_n \sum_{t \in F} x_t + \sum_{i=1}^{n-1} a_i x_i$ has the same sign as a_n .) Also, if $\mathbb{Z} = \bigcup_{i=1}^r B_i$ then $\mathbb{Z} = \bigcup_{i=1}^r (-B_i)$ so statement (a) holds for \vec{a} and \vec{b} if and only if it holds for $-\vec{a}$ and $-\vec{b}$. Thus we may assume that a_n and b_m are positive.

Let $\vec{c} = b_m \vec{a}$ and let $\vec{d} = a_n \vec{b}$. We claim that \vec{c} and \vec{d} satisfy statement (a). To see this, let $r \in \mathbb{N}$ and let $\mathbb{Z} = \bigcup_{i=1}^r B_i$. Pick $i \in \{1, 2, \ldots, r\}$ and sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} with $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty}) \subseteq B_i$. By passing to sum subsystems we may presume (using Lemma 3.3) that $FS(\langle x_t \rangle_{t=1}^{\infty}) \subseteq b_m \mathbb{N}$ and $FS(\langle y_t \rangle_{t=1}^{\infty}) \subseteq a_n \mathbb{N}$. For $t \in \mathbb{N}$, let $u_t = \frac{x_t}{b_m}$ and $v_t = \frac{y_t}{a_n}$ Then $MT(\vec{c}, \langle u_t \rangle_{t=1}^{\infty}) = MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty})$ and $MT(\vec{d}, \langle v_t \rangle_{t=1}^{\infty}) = MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty})$. Therefore we may assume that $a_n = b_m \in \mathbb{N}$ as claimed.

Now for $x \in \mathbb{Z} \setminus \{0\}$, let $G_P(x) = \{(t, u, \vec{v}) \in G(x) : (u, \vec{v}) \in P(x)\}$. For $x \in \mathbb{Z} \setminus \{0\}$ and $t \in \mathbb{N}$, let $R_t(x) = \{(t', u', \vec{v}') \in G_P(x) : t' < t\}$. For $x \in \mathbb{Z} \setminus \{0\}$ and $i \in \{0, 1, ..., k-1\}$, let

$$S_i(x) = \{(t, u, \vec{v}) \in G_P(x) : \pi(|R_t(x)|) = i\} \text{ and}$$

$$T_i(x) = \{(u, \vec{v}) \in \{1, 2, \cdots, p-1\} \times V : \pi(|\{t \in \mathbb{N} : (t, u, \vec{v}) \in S_i(x)\}|) = 1\}.$$

We define a coloring φ of \mathbb{Z} as follows. For $x, y \in \mathbb{Z}$, $\varphi(x) = \varphi(y)$ if and only if either x = y = 0 or $\lambda(x) = \lambda(y)$, $\rho(x) = \rho(y)$, $\pi(g_{(u,\vec{v})}(x)) = \pi(g_{(u,\vec{v})}(y))$ for every $(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V$, and $T_i(x) = T_i(y)$ for every $i \in \{0, 1, \dots, k-1\}$. Notice that φ is a finite coloring of \mathbb{Z} . Pick sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} such that $\varphi(x) = \varphi(y)$ for every $x \in MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty})$ and every $y \in MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty})$.

Now define a coloring ψ of \mathbb{Z} as follows. For $x, y \in \mathbb{Z}$, $\psi(x) = \psi(y)$ if and only if either x = y = 0 or

(1)
$$\rho(x) = \rho(y)$$
 and $\lambda(x) = \lambda(y)$;

- (2) for all $i \in \{1, 2, \dots, n\}$, $\rho(a_i x) = \rho(a_i y)$ and $\lambda(a_i x) = \lambda(a_i y)$;
- (3) for all $i \in \{1, 2, \dots, m\}$, $\rho(b_i x) = \rho(b_i y)$ and $\lambda(b_i x) = \lambda(b_i y)$;
- (4) for all $(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V$ and all $i \in \{1, 2, \dots, n\}, g_{(u, \vec{v})}(a_i x) \equiv g_{(u, \vec{v})}(a_i y)$ (mod k); and

(5) for all $(u, \vec{v}) \in \{1, 2, \dots, p-1\} \times V$ and all $i \in \{1, 2, \dots, m\}, g_{(u, \vec{v})}(b_i x) \equiv g_{(u, \vec{v})}(b_i y)$ (mod k).

Using Lemma 3.3 and passing to sum subsystems, we may presume that

- (a) $x_1 > p^{11}$ and $y_1 > p^{11}$;
- (b) for each $t \in \mathbb{N}$, min $(\operatorname{supp}(x_{t+1})) \ge 13 + \max(\operatorname{supp}(x_t))$ and min $(\operatorname{supp}(y_{t+1})) \ge 13 + \max(\operatorname{supp}(y_t))$; and
- (c) for all $x, x' \in FS(\langle x_t \rangle_{t=1}^{\infty})$ and all $y, y' \in FS(\langle y_t \rangle_{t=1}^{\infty})$, one has $\psi(x) = \psi(x')$ and $\psi(y) = \psi(y')$.

We have some $P \subseteq \{1, 2, \ldots, p-1\} \times V$ such that for all $x \in MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty})$ and all $y \in MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty}), P(x) = P(y) = P$, because $\pi(g_{(u,\vec{v})}(x)) = \pi(g_{(u,\vec{v})}(y))$ for all $(u, \vec{v}) \in \{1, 2, \ldots, p-1\} \times V$. Let $Q = \{(\rho(a_{j+1}x_{j+1}), \lambda(a_jx_j)) : j \in \{1, 2, \ldots, n-1\}\}$. We claim that P = Q. To see this, note that by Lemma 3.7 and conditions (2) and (4) of the definition of ψ , $\pi(g_{(u,\vec{v})}(a_ix_i)) \in \{0, k-1\}$ for all $(u, \vec{v}) \in \{1, 2, \ldots, p-1\} \times V$ and all $i \in \{1, 2, \ldots, n\}$. By Lemma 3.8, if $(u, \vec{v}) \in Q$, then $\pi(g_{(u,\vec{v})}(a_ix_i)) = 0$ for all $i \in \{1, 2, \ldots, n\}$.

Now let $x = a_n x_n + a_{n-1} x_{n-1} + \ldots + a_1 x_1$, so that P(x) = P. For any $(u, \vec{v}) \in \{1, 2, \ldots, p-1\} \times V$, we have $g_{(u,\vec{v})}(x) =$

$$\sum_{i=1}^{n} g_{(u,\vec{v})}(a_i x_i) + \left| \left\{ j \in \{1, 2, \dots, n-1\} : (u, \vec{v}) = \left(\rho(a_{j+1} x_{j+1}), \lambda(a_j, x_j) \right) \right\} \right|$$

Thus

(*) if
$$(u, \vec{v}) \in Q$$
, then
 $\pi(g_{(u,\vec{v})}(x)) = |\{j \in \{1, 2, ..., n-1\} : (u, \vec{v}) = (\rho(a_{j+1}x_{j+1}), \lambda(a_j, x_j))\}|.$

On the other hand, if $(u, \vec{v}) \notin Q$, then $g_{(u,\vec{v})}(x) = \sum_{i=1}^{n} g_{(u,\vec{v})}(a_i x_i)$ so either $\pi(g_{(u,\vec{v})}(x)) = 0$ or $\pi(g_{(u,\vec{v})}(x)) \in \{k - n, k - n + 1, \dots, k - 1\}$ so that $(u, \vec{v}) \notin P$. Thus P = Q as claimed. Similarly, $P = \{(\rho(b_{j+1}y_{j+1}), \lambda(b_j y_j)) : j \in \{1, 2, \dots, m - 1\}\}$.

Now using (*) and the corresponding assertion for $y = b_1y_1 + b_2y_2 + \ldots + b_my_m$, we have

$$n-1 = \sum_{(u,\vec{v})\in P(x)} \pi(g_{(u,\vec{v})}(x)) = \sum_{(u,\vec{v})\in P(y)} \pi(g_{(u,\vec{v})}(y)) = m-1$$

so
$$n = m$$

For $t \in \mathbb{N}$ and $z \in \mathbb{Z} \setminus \{0\}$, let

$$\delta_t(z) = \{ (t', u', \vec{v}') \in G(z) : t' < t \text{ and } (u', \vec{v}') \in Q \}.$$

Given $(u, \vec{v}) \in Q$, $i \in \{0, 1, \dots, k-1\}$, and $z \in \mathbb{Z} \setminus \{0\}$, let

$$\gamma_{(i,u,\vec{v})}(z) = \{t \in \mathbb{N} : (t, u, \vec{v}) \in G(z) \text{ and } \pi(|\delta_t(z)|) = i\}.$$

Using Lemma 3.3, choose a sum subsystem $\langle w_t \rangle_{t=1}^{\infty}$ of $\langle x_t \rangle_{t=1}^{\infty}$ such that for all $w, w' \in FS(\langle w_t \rangle_{t=1}^{\infty})$, all $(u, \vec{v}) \in Q$, all $s \in \{1, 2, ..., n\}$, and all $i \in \{0, 1, ..., k-1\}$, $|\gamma_{(i,u,\vec{v})}(a_s w)| \equiv |\gamma_{(i,u,\vec{v})}(a_s w')| \pmod{k}$.

Let $(u, \vec{v}) \in Q$, let $s \in \{1, 2, ..., n\}$, and let $i \in \{0, 1, ..., k-1\}$. We claim that $|\gamma_{(i,u,\vec{v})}(a_sw)| \equiv 0 \pmod{k}$ for all $w \in FS(\langle w_t \rangle_{t=1}^{\infty})$. For this it suffices to show that $\gamma_{(i,u,\vec{v})}(a_sw_2 + a_sw_1) = \gamma_{(i,u,\vec{v})}(a_sw_2) \cup \gamma_{(i,u,\vec{v})}(a_sw_1)$.

We note that $(\rho(a_sw_2), \lambda(a_sw_1)) \notin Q$. To see this, suppose instead that $(\rho(a_sw_2), \lambda(a_sw_1)) = (\rho(a_{j+1}x_{j+1}), \lambda(a_jx_j))$ for some $j \in \{1, 2, ..., n-1\}$. Since $w_1, w_2 \in FS(\langle x_t \rangle_{t=1}^{\infty})$, we have that $\rho(a_{j+1}x_{j+1}) = \rho(a_sw_2) = \rho(a_sx_{j+1})$ and $\lambda(a_jx_j) = \lambda(a_sw_1) = \lambda(a_sx_j)$. But then by Lemma 2.5, $a_{j+1} = a_s = a_j$ contradicting the fact that \vec{a} is a compressed sequence. Thus since $(\rho(a_sw_2), \lambda(a_sw_1)) \notin Q$,

$$\gamma_{(i,u,\vec{v})}(a_sw_2 + a_sw_1) = \{ t \in \mathbb{N} : (t, u, \vec{v}) \in G(a_sw_2) \text{ and } \pi(|\delta_t(a_sw_2 + a_sw_1)|) = i \} \cup \\ \{ t \in \mathbb{N} : (t, u, \vec{v}) \in G(a_sw_1) \text{ and } \pi(|\delta_t(a_sw_2 + a_sw_1)|) = i \} .$$

Now, if $(t, u, \vec{v}) \in G(a_s w_1)$, then $\delta_t(a_s w_2 + a_s w_1) = \delta_t(a_s w_1)$. If $(t, u, \vec{v}) \in G(a_s w_2)$, then (again using the fact that $(\rho(a_s w_2), \lambda(a_s w_1)) \notin Q$) we have $\delta_t(a_s w_2 + a_s w_1) = \delta_t(a_s w_2) \cup \delta_t(a_s w_1)$. Also for $(t, u, \vec{v}) \in G(a_s w_2)$,

$$\delta_t(a_s w_1) = \bigcup_{(u', \vec{v}') \in Q} \left\{ (t', u', \vec{v}') : t' \in G_{(u', \vec{v}')}(a_s w_1) \right\}$$

and so $|\delta_t(a_sw_1)| = \sum_{(u', \vec{v}') \in Q} g_{(u, \vec{v}')}(a_sw_1) \equiv 0 \pmod{k}$. Thus if $(t, u, \vec{v}) \in G(a_sw_2)$ we have $\pi(|\delta_t(a_sw_2 + a_sw_1)|) = \pi(|\delta_t(a_sw_2)|)$. Therefore $\gamma_{(i, u, \vec{v})}(a_sw_2 + a_sw_1) = \gamma_{(i, u, \vec{v})}(a_sw_2) \cup \gamma_{(i, u, \vec{v})}(a_sw_1)$ as required.

We shall complete the proof by showing that for any $x \in MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty})$, any $z \in FS(\langle x_t \rangle_{t=1}^{\infty})$, and any $i \in \{0, 1, \ldots, n-2\}$,

(†)
$$T_i(x) = \left\{ \left(\rho(a_{i+2}z), \lambda(a_{i+1}z) \right) \right\}.$$

Assume for now that we have done this. It will then follow similarly that for any $y \in MT(\vec{a}, \langle y_t \rangle_{t=1}^{\infty})$, any $q \in FS(\langle y_t \rangle_{t=1}^{\infty})$, and any $i \in \{0, 1, \ldots, n-2\}$, $T_i(y) = \{(\rho(b_{i+2}q), \lambda(b_{i+1}q))\}$. Since for such x, y, and i, we have $T_i(x) = T_i(y)$, we then must have in particular that $\lambda(a_{i+1}x_n) = \lambda(b_{i+1}y_n)$. We also have that

$$\lambda(a_n x_n) = \lambda(a_n x_n + a_{n-1} x_{n-1} + \dots + a_1 x_1) = \lambda(b_n y_n + b_{n-1} y_{n-1} + \dots + b_1 y_1) = \lambda(b_n y_n) = \lambda(a_n y_n) + \lambda(a_n y_n) + \lambda(a_n y_n) = \lambda(a_n y_n) + \lambda(a_n y_n) = \lambda(a_n y_n) + \lambda(a_n y_n) = \lambda(a_n y_n) + \lambda(a_n y_n) + \lambda(a_n y_n) = \lambda(a_n y_n) + \lambda(a_n y_n) + \lambda(a_n y_n) = \lambda(a_n y_n) + \lambda(a$$

Thus by Lemma 2.5(ii), we will have that $a_{i+1} = b_{i+1}$ for each $i \in \{0, 1, \ldots, n-2\}$. Since we already know that $a_n = b_n$, we will then have $\vec{a} = \vec{b}$.

To establish (†), let $x = a_n w_n + a_{n-1} w_{n-1} + \ldots + a_1 w_1$. We show that $T_i(x) = \{(\rho(a_{i+2}w_{i+2}), \lambda(a_{i+1}w_{i+1}))\}$ for each $i \in \{0, 1, \ldots, n-2\}$. Notice that if $i \in \{0, 1, \ldots, n-2\}$.

n-2 and $(u, \vec{v}) \in T_i(x)$, then $\{t \in \mathbb{N} : (t, u, \vec{v}) \in S_i(x)\} \neq \emptyset$ and so $(u, \vec{v}) \in P(x) = Q$. Consequently, for each $i \in \{0, 1, \dots, n-2\}$,

$$T_i(x) = \{(u, \vec{v}) \in Q : \pi(|\{t \in \mathbb{N} : (t, u, \vec{v}) \in S_i(x)\}|) = 1\}.$$

Let $(u, \vec{v}) = (\rho(a_{i+2}w_{i+2}), \lambda(a_{i+1}w_{i+1}))$, where $i \in \{0, 1, \ldots, n-2\}$. We consider $\{t \in \mathbb{N} : (t, u, \vec{v}) \in S_i(x)\}$. If $t = \min(\operatorname{supp}(a_{i+2}w_{i+2}))$, then $(t, u, \vec{v}) \in S_i(x)$, because it follows from Lemma 3.8 that $g_{(u,\vec{v})}(a_sw_s) \equiv 0 \pmod{k}$ for every $s \in \{1, 2, \ldots, n\}$. If $(t, u, \vec{v}) \in G(x)$ and $t = \min(\operatorname{supp}(a_{j+2}w_{j+2}))$, with $j \in \{0, 1, \ldots, n-2\} \setminus \{i\}$, then $(t, u, \vec{v}) \in S_j(x)$ and thus $(t, u, \vec{v}) \notin S_i(x)$. If $(t, u, \vec{v}) \in G(a_sw_s)$ for some $s \in \{1, 2, \ldots, n\}$, then $(t, u, \vec{v}) \in S_i(x)$ if and only if $t \in \gamma_{(j, u, \vec{v})}(a_sw_s)$, where $j + s - 1 \equiv i \pmod{k}$. We have seen that $|\gamma_{(j, u, \vec{v})}(a_sw_s)| \equiv 0 \pmod{k}$. So $|\{t \in \mathbb{N} : (t, u, \vec{v}) \in S_i(x)\}| \in 1 + k\omega$; i.e. $(u, \vec{v}) \in T_i(x)$.

Now let $(w, \vec{z}) \in P(x) \setminus \{(u, \vec{v})\}$. Then $(t, w, \vec{z}) \in S_i(x)$ if and only if $t \in \gamma_{(j,w,\vec{z})}(a_sw_s)$ for some $s \in \{1, 2, \dots, n\}$, where $j + s - 1 \equiv i \pmod{k}$. Since $|\gamma_{(j,w,\vec{z})}(a_sw_s)| \equiv 0 \pmod{k}, |\{t \in \mathbb{N} : (t, w, \vec{z}) \in S_i(x)\}| \in k\omega$ and so $(w, \vec{z}) \notin T_i(x)$.

Thus $T_i(x) = \{(u, \vec{v})\}$, and we have established that (†) holds.

In the proof of Theorem 3.1 we used a large number of colors. We observe now that in fact two colors suffice.

3.9 Corollary. Let \vec{a} and \vec{b} be finite compressed sequences with entries from $\mathbb{Z}\setminus\{0\}$ and assume that there is no positive rational number α such that $\vec{b} = \alpha \cdot \vec{a}$. Then there exist sets A and B such that $\mathbb{Z} = A \cup B$ and there is no sequence $\langle x_i \rangle_{i=1}^{\infty}$ with $MT(\vec{a}, \langle x_i \rangle_{i=1}^{\infty}) \subseteq B$ and there is no sequence $\langle y_i \rangle_{i=1}^{\infty}$ with $MT(\vec{b}, \langle y_i \rangle_{i=1}^{\infty}) \subseteq A$.

Proof. Pick by Theorem 3.1 $r \in \mathbb{N}$ and sets $\langle C_j \rangle_{j=1}^r$ such that $\mathbb{Z} = \bigcup_{j=1}^r C_j$ and for no $j \in \{1, 2, ..., r\}$ do there exist sequences $\langle x_i \rangle_{i=1}^{\infty}$ and $\langle y_i \rangle_{i=1}^{\infty}$ with $MT(\vec{a}, \langle x_i \rangle_{i=1}^{\infty}) \cup$ $MT(\vec{b}, \langle y_i \rangle_{i=1}^{\infty}) \subseteq C_j$. Let $A = \bigcup \{C_j : \text{there exists } \langle x_i \rangle_{i=1}^{\infty} \text{ with } MT(\vec{a}, \langle x_i \rangle_{i=1}^{\infty}) \subseteq C_j \}$ and let $B = \mathbb{N} \setminus A$. By Theorem 1.8 the sets A and B are as required. \Box

4. Equations in $\beta \mathbb{Z}$

The results of this paper are intimately related with the algebra in the Stone-Cech compactification $\beta \mathbb{Z}$ of \mathbb{Z} . Given any discrete semigroup (S, \cdot) , the operation extends to βS making $(\beta S, \cdot)$ a compact right topological semigroup with S contained in the topological center of βS . We take the points of βS to be the ultrafilters on S. See [8] for an elementary introduction to this structure, and for the meaning of any unfamiliar terms used here.

In particular, the operations + and \cdot on \mathbb{Z} both extend to $\beta\mathbb{Z}$ making $(\beta\mathbb{Z}, +)$ and $(\beta\mathbb{Z}, \cdot)$ right topological semigroups. The following theorem easily implies our Theorem 1.8. In this result it is important to note that, for example $2 \cdot p$ refers to the operation in $(\beta\mathbb{Z}, \cdot)$ and does not mean p + p.

4.1 Theorem. Let $\langle a_t \rangle_{t=1}^n$ be a sequence in $\mathbb{Z} \setminus \{0\}$, let p be an idempotent in $(\beta \mathbb{N}, +)$, and let $q = a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p$. Let $A \in p$ and $B \in q$. There exists a sequence $\langle x_i \rangle_{i=1}^{\infty}$ in \mathbb{N} with $FS(\langle x_i \rangle_{i=1}^{\infty}) \subseteq A$ and $MT(\vec{a}, \langle x_i \rangle_{i=1}^{\infty}) \subseteq B$.

Proof. [6, Lemma 3.4].

To derive Theorem 1.8 from Theorem 4.1, let a sequence $\langle y_i \rangle_{i=1}^{\infty}$ in \mathbb{N} be given, let $r \in \mathbb{N}$ and let $\mathbb{Z} = \bigcup_{j=1}^{r} B_j$. By passing to a sum subsystem if necessary, we may presume that for each $i, y_{i+1} > 4 \cdot \sum_{t=0}^{i} y_t$. Pick by [8, Lemma 5.11] an idempotent p with $FS(\langle y_i \rangle_{i=1}^{\infty}) \in p$ and let $q = a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p$. Pick $j \in \{1, 2, \ldots, r\}$ such that $B_j \in q$ and pick a sequence $\langle x_i \rangle_{i=1}^{\infty}$ with $FS(\langle x_i \rangle_{i=1}^{\infty}) \subseteq FS(\langle y_i \rangle_{i=1}^{\infty})$ and $MT(\vec{a}, \langle y_i \rangle_{i=1}^{\infty}) \subseteq B_j$. Since we had for each $i, y_{i+1} > 4 \cdot \sum_{t=0}^{i} y_t$, one easily sees (using [6, Lemma 3.5], for example) that $\langle x_i \rangle_{i=1}^{\infty}$ is in fact a sum subsystem of $\langle y_i \rangle_{i=1}^{\infty}$.

Amir Maleki observed in [10, Theorem 2.19] that the results of [3] implied that if $\langle a_1, a_2, \ldots, a_n \rangle$ and $\langle b_1, b_2, \ldots, b_m \rangle$ are distinct compressed sequences in \mathbb{N} , then the equation $a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot p + b_2 \cdot p + \ldots + b_m \cdot p$ has no solutions with pan idempotent in $(\beta \mathbb{N}, +)$. (He also showed in [10, Theorem 2.7] that this equation also has no solutions if p is right cancellable in $(\beta \mathbb{N}, +)$.) We see now that the corresponding assertion holds where the entries of \vec{a} and \vec{b} are allowed to be negative.

4.2 Corollary. Let $\langle a_1, a_2, \dots, a_n \rangle$ and $\langle b_1, b_2, \dots, b_m \rangle$ be compressed sequences in $\mathbb{Z} \setminus \{0\}$, let $p+p = p \in \beta \mathbb{N}$, and assume that $a_1 \cdot p + a_2 \cdot p + \dots + a_n \cdot p = b_1 \cdot p + b_2 \cdot p + \dots + b_m \cdot p$. then $\vec{a} = \vec{b}$.

Proof. We show first that it suffices to show that there is some positive rational number α such that $\vec{b} = \alpha \cdot \vec{a}$. Let $\alpha = \frac{r}{s}$ where $r, s \in \mathbb{N}$. Then by [8, Lemma 13.1] (which is the only nontrivial instance of the distributive law known to hold in $\beta\mathbb{Z}$), we have that

 $r \cdot (a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p) = s \cdot (b_1 \cdot p + b_2 \cdot p + \ldots + b_m \cdot p).$

Since also $s \cdot (a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p) = s \cdot (b_1 \cdot p + b_2 \cdot p + \ldots + b_m \cdot p)$, we have by [8, Lemma 6.28] that r = s.

Therefore, by Theorem 3.1, it suffices to show that whenever $r \in \mathbb{N}$ and $\mathbb{Z} = \bigcup_{i=1}^{r} B_{j}$, there exist $j \in \{1, 2, \ldots, r\}$ and sequences $\langle x_{i} \rangle_{i=1}^{\infty}$ and $\langle y_{i} \rangle_{i=1}^{\infty}$ with

 $MT(\vec{a}, \langle x_i \rangle_{i=1}^{\infty}) \cup MT(\vec{b}, \langle y_i \rangle_{i=1}^{\infty}) \subseteq B_i$. To this end pick $j \in \{1, 2, \dots, r\}$ such that $B_j \in a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p$ and apply Theorem 4.1.

We shall see in Theorem 4.4 that one can expand the list of equivalent conditions in Theorem 3.1. One of the added conditions involves idempotents in the smallest ideal $K(\beta\mathbb{N}, +)$ of $(\beta\mathbb{N}, +)$, the so called *minimal* idempotents. These are combinatorially significant because the members of minimal idempotents are *central* sets and are guaranteed to have rich combinatorial structure. (See [8, Chapter 14].)

The following lemma is not new, but does not seem to be in [8].

4.3 Lemma. Let r be an idempotent in $K(\beta\mathbb{N}, +)$ and let $k \in \mathbb{N}$. Then $k \cdot r$ is an idempotent in $K(\beta\mathbb{N}, +)$.

Proof. The function $p \mapsto k \cdot p$ from $\beta \mathbb{N}$ onto $k \cdot \beta \mathbb{N}$ is a continuous homomorphism. (It is continuous because λ_k is continuous in $(\beta \mathbb{N}, \cdot)$ and it is a homomorphism by [8, Lemma 13.1].) It maps $K(\beta \mathbb{N}, +)$ onto $K(k \cdot \beta \mathbb{N}, +)$. Now $k \cdot \beta \mathbb{N}$ contains all the idempotents of $\beta \mathbb{N}$ by [8, Lemma 6.6], and therefore meets $K(\beta \mathbb{N}, +)$. It follows from [8, Theorem 1.65] that $K(k \cdot \beta \mathbb{N}, +) \subseteq K(\beta \mathbb{N}, +)$.

4.4 Theorem. Let $\vec{a} = \langle a_1, a_2, \ldots, a_n \rangle$ and $\vec{b} = \langle b_1, b_2, \ldots, b_m \rangle$ be finite compressed sequences with entries from $\mathbb{Z} \setminus \{0\}$. The following statements are equivalent.

- (a) Whenever $r \in \mathbb{N}$ and $\mathbb{Z} = \bigcup_{i=1}^{r} B_i$, there exist $i \in \{1, 2, \ldots, r\}$ and sequences $\langle x_t \rangle_{t=1}^{\infty}$ and $\langle y_t \rangle_{t=1}^{\infty}$ in \mathbb{N} with $MT(\vec{a}, \langle x_t \rangle_{t=1}^{\infty}) \cup MT(\vec{b}, \langle y_t \rangle_{t=1}^{\infty}) \subseteq B_i$.
- (b) There is a positive rational number α such that $\vec{b} = \alpha \cdot \vec{a}$.
- (c) There exist idempotents p and q in $K(\beta \mathbb{N}, +)$ such that $a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot q + b_2 \cdot q + \ldots + b_m \cdot q$.
- (d) There exist idempotents p and q in $(\beta \mathbb{N}, +)$ such that $a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot q + b_2 \cdot q + \ldots + b_m \cdot q$.

Proof. We have by Theorem 3.1 that (a) and (b) are equivalent and (c) trivially implies (d). By Theorem 4.1 (d) implies (a) (by choosing $i \in \{1, 2, ..., r\}$ such that $B_i \in a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot q + b_2 \cdot q + \ldots + b_m \cdot q)$.

To see that (b) implies (c), pick $k, l \in \mathbb{N}$ such that $\vec{b} = \frac{k}{l} \cdot \vec{a}$. Pick any idempotent $r \in K(\beta\mathbb{N})$. Let $p = k \cdot r$ and $q = l \cdot r$. By Lemma 4.3 p and q are idempotents in $K(\beta\mathbb{N}, +)$. Then $a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = a_1 \cdot k \cdot r + a_2 \cdot k \cdot r + \ldots + a_n \cdot k \cdot r = b_1 \cdot l \cdot r + b_2 \cdot l \cdot r + \ldots + b_n \cdot l \cdot r = b_1 \cdot q + b_2 \cdot q + \ldots + b_m \cdot q$.

We remark that Corollary 3.9 is equivalent to the following statement: if \vec{a} and \vec{b} satisfy the hypotheses of this corollary, there exists sets A and B such that $\mathbb{Z} = A \cup B$

and there is no idempotent $p \in \beta \mathbb{N}$ for which $B \in a_1 \cdot p + a_2 \cdot p + \dots + a_n \cdot p$ and no idempotent $q \in \beta \mathbb{N}$ for which $A \in b_1 \cdot q + b_2 \cdot q + \dots + b_m \cdot q$. This is a property which distinguishes idempotents from other elements of \mathbb{N}^* . Suppose that $\vec{a} = \langle a_1, a_2, \dots, a_n \rangle$ and $\vec{b} = \langle b_1, b_2, \dots, b_m \rangle$ are arbitrary finite sequences in $\mathbb{Z} \setminus \{0\}$, with $a_n, b_m \in \mathbb{N}$ and $\sum_{i=1}^n a_i, \sum_{i=1}^m b_i \neq 0$. Then it follows from results in [6] that, in any finite colouring of \mathbb{N} , there exist $p, q \in \mathbb{N}^*$ such that $a_1 \cdot p + a_2 \cdot p + \dots + a_n \cdot p$ and $b_1 \cdot q + b_2 \cdot q + \dots + b_m \cdot q$ have the same monochrome set as a member. We can even require that p and q have rapidly increasing sets as members, where we call a subset $\{t_n : n \in \mathbb{N}\}$ of \mathbb{N} rapidly increasing if $t_{n+1} - t_n \to \infty$. However, if p and q have rapidly increasing sets as members, it is quite easy to prove that the equation $a_1 \cdot p + a_2 \cdot p + \dots + a_n \cdot p = b_1 \cdot q + b_2 \cdot q + \dots + b_m \cdot q$ can only hold if \vec{b} is a positive rational multiple of \vec{a} .

We conclude by modifying [7, Question 1.5] (which remains unanswered) to allow for negative entries.

4.5 Question. Let $\langle a_1, a_2, \ldots, a_n \rangle$ and $\langle b_1, b_2, \ldots, b_m \rangle$ be compressed sequences in $\mathbb{Z} \setminus \{0\}$. Suppose that there exists some $p \in \mathbb{N}^*$ such that

$$a_1 \cdot p + a_2 \cdot p + \ldots + a_n \cdot p = b_1 \cdot p + b_2 \cdot p + \ldots + b_m \cdot p$$
.

Must it then be true that $\vec{a} = \vec{b}$?

We note that it can be shown that this equation implies that $a_1 = b_1$ and $a_n = b_m$. The implication $a_n = b_m$ was shown in [7] in the case in which $a_n, b_m > 0$, and it is easy to see that we can assume this. The implication $a_1 = b_1$ was also shown in [7] in the case in which $a_1, b_1 > 0$, and the proof in [7] extends easily to the general case.

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